

AKU B.E./B.Tech EE Sem 3 syllabus

Electrical Circuit Analysis

PCC-EE01 Electrical Circuit Analysis

4 credits

Module 1: Network Theorems

Superposition theorem, Thevenin theorem, Norton theorem, Maximum power transfer theorem, Reciprocity theorem, Compensation theorem. Analysis with dependent current and voltage sources. Node and Mesh Analysis. Concept of duality and dual networks.

Module 2: Solution of First and Second order networks

Solution of first and second order differential equations for Series and parallel R-L, R-C, R-L-C circuits, initial and final conditions in network elements, forced and free response, time constants, steady state and transient state response.

Module 3: Sinusoidal steady state analysis

Representation of sine function as rotating phasor, phasor diagrams, impedances and admittances, AC circuit analysis, effective or RMS values, average power and complex power. Three-phase circuits. Mutual coupled circuits, Dot Convention in coupled circuits, Ideal Transformer.

Module 4: Electrical Circuit Analysis Using Laplace Transforms

Review of Laplace Transform, Analysis of electrical circuits using Laplace Transform for standard inputs, convolution integral, inverse Laplace transform, transformed network with initial conditions. Transfer function representation. Poles and Zeros. Frequency response (magnitude and phase plots), series and parallel resonances

Module 5: Two Port Network and Network Functions

Two Port Networks, terminal pairs, relationship of two port variables,

impedance parameters, admittance parameters, transmission parameters and hybrid parameters, interconnections of two port networks.

Text / References:

1. M. E. Van Valkenburg, "Network Analysis", Prentice Hall, 2006.
2. D. Roy Choudhury, "Networks and Systems", New Age International Publications, 1998.
3. W. H. Hayt and J. E. Kemmerly, "Engineering Circuit Analysis", McGraw Hill Education, 2013.
4. C. K. Alexander and M. N. O. Sadiku, "Electric Circuits", McGraw Hill Education, 2004.
5. K. V. V. Murthy and M. S. Kamath, "Basic Circuit Analysis", Jaico Publishers, 1999.

Analog Electronic Circuits

PCC-EE03 Analog Electronic Circuits

3 credits

Module 1: Diode circuits

P-N junction diode, I-V characteristics of a diode; review of half-wave and full-wave rectifiers, Zener diodes, clamping and clipping circuits.

Module 2: BJT circuits

Structure and I-V characteristics of a BJT; BJT as a switch. BJT as an amplifier: small-signal model, biasing circuits, current mirror; common-emitter, common-base and common-collector amplifiers; Small signal equivalent circuits, high-frequency equivalent circuits

Module 3: MOSFET circuits

MOSFET structure and I-V characteristics. MOSFET as a switch. MOSFET as an amplifier: small-signal model and biasing circuits, common-source, common-gate and common-drain amplifiers; small signal equivalent circuits - gain, input and output impedances, trans-conductance, high frequency equivalent circuit.

Module 4: Differential, multi-stage and operational amplifiers

Differential amplifier; power amplifier; direct coupled multi-stage amplifier; internal structure of an operational amplifier, ideal op-amp, non-idealities in an op-amp (Output offset voltage, input bias current, input offset current, slew rate, gain bandwidth product)

Module 5: Linear applications of op-amp

Idealized analysis of op-amp circuits. Inverting and non-inverting amplifier, differential amplifier, instrumentation amplifier, integrator, active filter, P,PI and PID controllers and lead/lag compensator using an op-amp, voltage regulator, oscillators (Wein bridge and phase shift).

Analog to Digital Conversion.

Module 6: Nonlinear applications of op-amp

Hysteretic Comparator, Zero Crossing Detector, Square-wave and triangular-wave generators. Precision rectifier, peak detector. Monoshot.

Text/References:

1. A. S. Sedra and K. C. Smith, "Microelectronic Circuits", New York, Oxford University Press, 1998.
2. J. V. Wait, L. P. Huelsman and G. A. Korn, "Introduction to Operational Amplifier theory and applications", McGraw Hill U. S., 1992.
3. J. Millman and A. Grabel, "Microelectronics", McGraw Hill Education, 1988.
4. P. Horowitz and W. Hill, "The Art of Electronics", Cambridge University Press, 1989.
5. P.R. Gray, R.G. Meyer and S. Lewis, "Analysis and Design of Analog Integrated Circuits", John Wiley & Sons, 2001.

Electrical Machines-I

PCC-EE05 Electrical Machines-I

4 credits

Module 1: Magnetic fields and magnetic circuits

Review of magnetic circuits - MMF, flux, reluctance, inductance; review of Ampere Law and Biot Savart Law; Visualization of magnetic fields produced by a bar magnet and a current carrying coil - through air and through a combination of iron and air; influence of highly permeable materials on the magnetic flux lines.

Module 2: Electromagnetic force and torque

B-H curve of magnetic materials; flux-linkage vs current characteristic of magnetic circuits; linear and nonlinear magnetic circuits; energy stored in the magnetic circuit; force as a partial derivative of stored energy with respect to position of a moving

element; torque as a partial derivative of stored energy with respect to angular position of a rotating element. Examples - galvanometer coil, relay contact, lifting magnet, rotating element with eccentricity or saliency

Module 3: Transformers

Principle, construction and operation of single-phase transformers, equivalent circuit, phasor diagram, voltage regulation, losses and efficiency Testing - open circuit and short circuit tests, polarity test, back-to-back test, separation of hysteresis and eddy current losses Three-phase transformer - construction, types of connection and their comparative features, Parallel operation of single-phase and three-phase transformers, Autotransformers - construction, principle, applications and comparison with two winding transformer, Magnetizing current, effect of nonlinear B-H curve of magnetic core material, harmonics in magnetization current, Phase conversion - Scott connection, three-phase to six-phase conversion, Tap-changing transformers - No-load and on-load tap-changing of transformers, Three-winding transformers. Cooling of transformers.

Module 4: DC machines

Basic construction of a DC machine, magnetic structure - stator yoke, stator poles, pole-faces or shoes, air gap and armature core, visualization of magnetic field produced by the field winding excitation with armature winding open, air gap flux density distribution, flux per pole, induced EMF in an armature coil. Armature winding and commutation - Elementary armature coil and commutator, lap and wave windings, construction of commutator, linear commutation Derivation of back EMF equation, armature MMF wave, derivation of torque equation, armature reaction, air gap flux density distribution with armature reaction.

Module 5: DC machine - motoring and generation

Armature circuit equation for motoring and generation, Types of field excitations - separately excited, shunt and series. Open circuit characteristic of separately excited DC generator, back EMF with armature reaction, voltage build-up in a shunt generator, critical field resistance and critical speed. V-I characteristics and torque-speed characteristics of separately excited, shunt and series motors. Speed control through armature voltage. Losses, load testing and back-to-back testing of DC machines

Text / References:

1. A. E. Fitzgerald and C. Kingsley, "Electric Machinery", New York,

McGraw Hill Education, 2013.

2. A. E. Clayton and N. N. Hancock, "Performance and design of DC machines", CBS Publishers, 2004.

3. M. G. Say, "Performance and design of AC machines", CBS Publishers, 2002.

4. P. S. Bimbhra, "Electrical Machinery", Khanna Publishers, 2011.

5. I. J. Nagrath and D. P. Kothari, "Electric Machines", McGraw Hill Education, 2010.

Electromagnetic Fields

PCC-EE07 Electromagnetic Fields

4 credits

Module 1: Review of Vector Calculus

Vector algebra-addition, subtraction, components of vectors, scalar and vector multiplications, triple products, three orthogonal coordinate systems (rectangular, cylindrical and spherical). Vector calculus-differentiation, partial differentiation, integration, vector operator del, gradient, divergence and curl; integral theorems of vectors. Conversion of a vector from one coordinate system to another.

Module 2: Static Electric Field

Coulomb's law, Electric field intensity, Electrical field due to point charges. Line, Surface and Volume charge distributions. Gauss law and its applications. Absolute Electric potential, Potential difference, Calculation of potential differences for different configurations. Electric dipole, Electrostatic Energy and Energy density.

Module 3: Conductors, Dielectrics and Capacitance

Current and current density, Ohms Law in Point form, Continuity of current, Boundary conditions of perfect dielectric materials.

Permittivity of dielectric materials, Capacitance, Capacitance of a two wire line, Poisson's equation, Laplace's equation, Solution of Laplace and Poisson's equation, Application of Laplace's and Poisson's equations.

Module 4: Static Magnetic Fields

Biot-Savart Law, Ampere Law, Magnetic flux and magnetic flux density, Scalar and Vector Magnetic potentials. Steady magnetic fields produced by current carrying conductors.

Module 5: Magnetic Forces, Materials and Inductance

Force on a moving charge, Force on a differential current element, Force between differential current elements, Nature of magnetic materials, Magnetization and permeability, Magnetic boundary conditions, Magnetic circuits, inductances and mutual inductances.

Module 6: Time Varying Fields and Maxwell's Equations

Faraday's law for Electromagnetic induction, Displacement current, Point form of Maxwell's equation, Integral form of Maxwell's equations, Motional Electromotive forces. Boundary Conditions.

Module 7: Electromagnetic Waves

Derivation of Wave Equation, Uniform Plane Waves, Maxwell's equation in Phasor form, Wave equation in Phasor form, Plane waves in free space and in a homogenous material. Wave equation for a conducting medium, Plane waves in lossy dielectrics, Propagation in good conductors, Skin effect. Poynting theorem.

Text / References:

1. M. N. O. Sadiku, "Elements of Electromagnetics", Oxford University Publication, 2014.
2. A. Pramanik, "Electromagnetism - Theory and applications", PHI Learning Pvt. Ltd, NewDelhi, 2009.
3. A. Pramanik, "Electromagnetism-Problems with solution", Prentice Hall India, 2012.
4. G.W. Carter, "The electromagnetic field in its engineering aspects", Longmans, 1954.
5. W.J. Duffin, "Electricity and Magnetism", McGraw Hill Publication, 1980.
6. W.J. Duffin, "Advanced Electricity and Magnetism", McGraw Hill, 1968.
7. E.G. Cullwick, "The Fundamentals of Electromagnetism", Cambridge University Press, 1966.
8. B. D. Popovic, "Introductory Engineering Electromagnetics", Addison-Wesley Educational Publishers, International Edition, 1971.
9. W. Hayt, "Engineering Electromagnetics", McGraw Hill Education, 2012.

Engineering Mechanics

ESC 201 Engineering Mechanics

4 credits

Module 1: Introduction to vectors and tensors and co-ordinate systems

Introduction to vectors and tensors and coordinate systems; Vector and tensor algebra; Indical notation; Symmetric and anti-symmetric tensors; Eigenvalues and Principal axes.

Module 2: Three-dimensional Rotation

Three-dimensional rotation: Euler's theorem, Axis-angle formulation and Euler angles; Coordinate transformation of vectors and tensors.

Module 3: Kinematics of Rigid Body

Kinematics of rigid bodies: Definition and motion of a rigid body; Rigid bodies as coordinate systems; Angular velocity of a rigid body, and its rate of change; Distinction between two- and three-dimensional rotational motion; Integration of angular velocity to find orientation; Motion relative to a rotating rigid body: Five term acceleration formula.

Module 4: Kinetics of Rigid Bodies

Kinetics of rigid bodies: Angular momentum about a point; Inertia tensor: Definition and computation, Principal moments and axes of inertia, Parallel and perpendicular axes theorems; Mass moment of inertia of symmetrical bodies, cylinder, sphere, cone etc., Area moment of inertia and Polar moment of inertia, Forces and moments; Newton-Euler's laws of rigid body motion.

Module 5: Free Body Diagram

Free body diagrams; Examples on modelling of typical supports and joints and discussion on the kinematic and kinetic constraints that they impose.

Module 6: General Motion

Examples and problems. General planar motions. General 3-D motions. Free precession, Gyroscopes, Rolling coin.

Module 7: Bending Moment

Transverse loading on beams, shear force and bending moment in beams, analysis of cantilevers, simply supported beams and overhanging beams, relationships between loading, shear force and bending moment, shear force and bending moment diagrams.

Module 8: Torsional Motion

Torsion of circular shafts, derivation of torsion equation, stress and deformation in circular and hollow shafts.

Module 9: Friction

Concept of Friction; Laws of Coulomb friction; Angle of Repose; Coefficient of friction.

Text / References:

1. J. L. Meriam and L. G. Kraige, "Engineering Mechanics: Dynamics", Wiley, 2011.
2. M. F. Beatty, "Principles of Engineering Mechanics", Springer Science & Business Media, 1986.

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